

# Doporučené nastavení BETAFLIGHT Recommended setting BETAFLIGHT

## Modes

WIKI

Use ranges to define the switches on your transmitter and corresponding mode assignments. A receiver channel that gives a reading between a range min/max will activate the mode. Remember to save your settings using the Save button.

Show/hide unused modes

ARM AUX 1

Min: 1300 Max: 1700

900 1000 1200 1400 1500 1600 1800 2000 2100

Add Range

**BETAFLIGHT**  
Configurator: 10.4.0  
Firmware: BTF 4.0.6 (Target: SPEV)

0.4 V

Gyro Accel Mag Baro GPS Sonar

No dataflash chip found

Enable Expert Mode Disconnect

Please close the configurator window before updating. Show Log

Setup Ports Configuration Power & Battery **PID Tuning** Receiver Modes Motors Blackbox CLI

Profile: Profile 1 Rateprofile: Rateprofile 1

Copy profile values Copy rateprofile values Reset all profile values Show all PIDs

**PID Settings** Filter Settings

	Proportional	Integral	Derivative	Feedforward	RC Rate	Super Rate	Max Vel [deg/s]	RC Expo
Basic/Acro								
ROLL	15	0	0	0	1,00	0,70	667	0,00
PITCH	0	0	0	0	1,00	0,70	667	0,00
YAW	0	0	0	0	1,00	0,70	667	0,00

Angle/Horizon

	Strength	Transition
Angle		50
Horizon		50
	Angle Limit	55

Rates

800 deg/s

0 deg/s 667 deg/s

0 deg/s 667 deg/s

0 deg/s 667 deg/s

Refresh Save

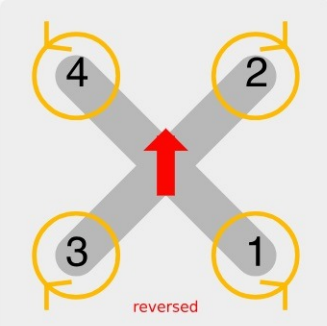
## Configuration

WIKI

**Note:** Not all combinations of features are valid. When the flight controller firmware detects invalid feature combinations conflicting features will be disabled.  
**Note:** Configure serial ports **before** enabling the features that will use the ports.

Mixer

Quad X



ESC/Motor Features

BRUSHED ESC/Motor protocol

Motor PWM speed Separated from PID speed

**MOTOR\_STOP** Don't spin the motors when armed

1000 Minimum Throttle (Lowest ESC value when armed)

2000 Maximum Throttle (Highest ESC value when armed)

1000 Minimum Command (ESC value when disarmed)